

Omar Elnaggar Researcher · Educator · Engineer · Entrepreneur 89a London Road, Liverpool, L3 8JA, United Kingdom ↓ +44 (0) 73077 22224 Somar.elnaggar@liverpool.ac.uk



2017-2018

### **SUMMARY**

A doctoral researcher with an avid interest in smart healthcare and machine learning, and pursuing a personal passion for teaching and learning. Aspired to a career where research and teaching meet at one sweet spot, and where I can demonstrate my growing management and entrepreneurial skills.

## **EDUCATION** \_

| Doctor of Philosophy in Mechanical, Materials and Aerospace Engineering<br>UNIVERSITY OF LIVERPOOL                           | 2019 - Present |
|--|----------------|
| Dissertation title: Wearable Sensing for non-Invasive Human Pose and Movement Analysis D                                     | URING SLEEP    |
| • In collaboration with an orthopaedic consultant at Liverpool University Hospitals NHS Foundation <sup>-</sup>              | Frust.         |
| Master of Engineering in Mechatronic Engineering<br>UNIVERSITY OF NOTTINGHAM   | 2015-2019      |
| • Best student award - rank 1/80   |                |
| • First Class with Honours   |                |
| Dissertation title: VOLITIONAL CONTROL OF UPPER LIMB PROSTHESIS FOR REHABILITATION SERVICES                                  |                |
| International Baccalaureate Diploma<br>AL-WAKRA INDEPENDENT SECONDARY SCHOOL FOR BOYS<br>• Ranked among the top 2% worldwide | 2013-2015      |
| Qatari High School Certificate   | 2013-2015      |
| AL-WAKRA INDEPENDENT SECONDARY SCHOOL FOR BOYS   |                |
| • Overall mark: 97%  |                |
| MEMBERSHIPS  |                |
| The Higher Education Academy (Advance HE)<br>ASSOCIATE FELLOW  | 2023 - Present |
| Institute of Electrical and Electronics Engineers MEMBER   | 2019 - Present |
| Awards and Achievements  |                |
| Winner of the "Build your own business 3" Pitch Contest (aka Launch £10,000 Program  | nme) 2021      |
| University College London  |                |
| EPSRC Funded PhD Studentship   | 2019           |
| University of Liverpool Doctoral Network in AI for Future Digital Health   |                |
| Japanese Government (MEXT) Postgraduate Scholarship  | 2019           |
| The Ministry of Education, Culture, Sports, Science and Technology (MEXT)  |                |
| Best Engineering Student Award   | 2019           |
| IEEE Electronics Packaging Society Malaysia Chapter  |                |
| Best Engineering Undergraduate Final Year Project - Finalist   | 2019           |
| The Institution of Engineering and Technology (UK) and The Institution of Engineering (Malaysia)                             |                |
| Best Student in MEng in Mechatronic Engineering (Year 3) Award   | 2017-2018      |

**Greenbulb Energy Prize for Outstanding Performance: Control Systems Design** The University of Nottingham and Greenbulb Energy Pte. Ltd.

The University of Nottingham

| Dean's Excellence Scholarship Award                                       | 2017-2018 |
|---|-----------|
| The University of Nottingham  |           |
| Department Undergraduate Development Scheme                               | 2018      |
| The University of Nottingham  |           |
| Certificate of Recognition: Mechatronic Engineering Course Representative | 2018      |
| The University of Nottingham  |           |
| Certificate of Recognition: Mechatronic Engineering Course Representative | 2019      |
| The University of Nottingham  |           |
| Department Undergraduate Development Scheme                               | 2016      |
| The University of Nottingham  |           |
| Freescale Cup Intelligent Car Competition - Finalist                      | 2016      |
| NXP Semiconductors  |           |
| High Achievers Scholarship Award  | 2015-2016 |
| The University of Nottingham  |           |
| Government Excellence Sponsorship   | 2013-2015 |
| Ministry of Education and Higher Education Qatar                          |           |
| Certificate of Excellence   | 2014      |
| Al-Wakra Independent Secondary School for Boys                            |           |
| French Language DELF A1 Proficiency Exam - Top Scorers Award              | 2014      |
| The French Council (Qatar)  |           |
| Certificate of Excellence   | 2013      |
| Al-Wakra Independent Secondary School for Boys                            |           |

## **RESEARCH FUNDING**

## Studentainment - Game-based Virtual Laboratories for Engineering Higher Education

Funding Body: University of Sheffield
Date Advised Funding was Secured: Mar 2022
Project Start Date: Sep 2022
Length of Project: 1.25 years (ends Dec 2023)
Grant Total: £7,698
Involvement: Co-Investigator
Other Investigators: Roselina Arelhi **Foot-ZZ - Clinical validation of a novel wearable sensor network for in-bed postural analysis**Funding Body: British Orthopaedic Foot and Ankle Society

Date Advised Funding was Secured: Sep 2022 Project Start Date: Jan 2023 Length of Project: 3 years (ends Dec 2026) Grant Total: £15,000 Involvement: Co-Investigator Other Investigators: Lyndon Mason and Paolo Paoletti

## **RESEARCH PUBLICATIONS**

O. Elnaggar, A. Hopkinson, F. Coenen, and P. Paoletti, *Sensor-enabled Sleep Posture Analysis: State-of-the-art and Opportunities of Wearable Technologies from Clinical, Sensing and Intelligent Perception Perspectives*, Biomedical Robots and Devices in Healthcare: Opportunities and Challenges for Future Applications, 2024. [Book chapter under second peer review by Elsevier]

O. Elnaggar, F. Coenen, A. Hopkinson, L. Mason, and P. Paoletti, *Sleep Posture One-Shot Learning Framework based on Extremity Joint Kinematics: In-Silico and In-Vivo Case Studies*, Information Fusion, 2023. [Link to Paper]

O. Elnaggar, R. Arelhi, F. Coenen, A. Hopkinson, L. Mason, and P. Paoletti, *KIDS: Kinematics-based (In)activity Detection and Segmentation in a Sleep Case Study*, Scientific Reports, 2023. [Link to preprint]

O. Elnaggar, F. Coenen, A. Hopkinson, L. Mason, and P. Paoletti, *Sleep Posture Classification: From In-Silico Proof-of-concept to Validation with Wearable Sensors*, Insigneo Showcase, United Kingdom, 2022. [Link to Poster]

O. Elnaggar, F. Coenen, A. Hopkinson, and P. Paoletti, *Generalised Joint Kinematic Analysis and 3D Visualisation: A Human Wrist Case Study*, BioMedEng22 Conference, United Kingdom, 2022. [Link to Abstract]

O. Elnaggar, F. Coenen, A. Hopkinson, and P. Paoletti, *Perception of Sleeping Poses Using Extremity Limb Orientations*, BioMedEng21 Conference Proceedings, United Kingdom, 2021. [Link to Abstract]

O. Elnaggar, F. Coenen, and P. Paoletti, *In-Bed Human Pose Classification Using Sparse Inertial Signals*, 40<sup>th</sup> International Conference on Innovative Techniques and Applications of Artificial Intelligence, Springer, Cham, 2020. [Link to Paper]

O. Elnaggar, F. Coenen, and P. Paoletti, *Wearable Sensing For Non-invasive Human Pose Recognition During Sleep*, AI for Future Digital Health Workshop, SGAI 40<sup>th</sup> International Conference on Artificial Intelligence, 2020. [Link to Video]

O. Elnaggar, and R. Arelhi, *A New Unsupervised Short-Utterance based Speaker Identification Approach with Parametric t-SNE Dimensionality Reduction*, International Conference on Artificial Intelligence in Information and Communication (ICAIIC), Japan, 2019. [Link to Paper]

O. Elnaggar, and R. Arelhi, *An Unsupervised Speaker Identification Approach: A Breakthrough 3D Visualization of High Dimensional Features*, 21<sup>st</sup> International Conference on Artificial Intelligence and Pattern Recognition (ICAIPR), Singapore, 2019. [Link to Paper]

### **TEACHING PUBLICATIONS**

O. Elnaggar, and R. Arelhi, *Game-based Learning in Engineering Education: How can we reconcile seemingly conflicting interests of students, academics, universities and national policy makers?*, BERA (British Educational Research Association) Conference, United Kingdom, 2022. [accepted]

O. Elnaggar, and R. Arelhi, *Design and Development of Game-based Learning for Virtual Engineering Laboratories: Two Case Studies*, AdvanceHE Teaching and Learning Conference, United Kingdom, 2022. [accepted]

O. Elnaggar, and R. Arelhi, *Quantification of Knowledge Exchange Within Classrooms: An AI-based Approach*, 9<sup>th</sup> European Conference on Education, United Kingdom, 2021. [Link to Paper]

#### **EMPLOYMENT HISTORY**

#### The University of Sheffield

Independent Consultant - Educational Technology

- Initiated and led the development of new instructional technologies for engineering laboratories.
- Delivered tools to support student learning experience, such as digital Game-based Learning and animations.
- Designed appropriate criteria for automated assessment of students' work and provision of quality feedback.

#### Contact: Dr. Roselina Arelhi - R.Arelhi@sheffield.ac.uk

#### VirLaber Ltd

Founder and Chief Technology Officer

- Established collaborations with academics in and out of UK to help them improve their quality of teaching.
- Led the development of a number of virtual labs for Engineering and Computer Science modules.
- Won a national judged pitching contest in the UK.

#### **Mindset Spinoff**

Content Creation Director (Project Initiative)

- Recruited a team of talented professionals in the field of Media Production.
- Managed the production of creative digital content on education and self-development topics.

03/2022 - Present | England

08/2021 - Present | Dubai

08/2021 - Present | England

## The University of Sheffield

#### Graduate Research Assistant

- Joined a university-wide research project on the curriculum design and delivery of engineering programmes.
- Proposed a novel pedagogical framework to stimulate student-to-student interaction and knowledge exchange.
- Employed machine learning to assess, qualitatively and quantitatively, the efficacy of pedagogical frameworks.
- Supervised a team of four interns to design and incorporate Game-based Learning in Engineering Education.

• Published and presented first-authored papers at leading teaching and learning conferences.

Contact: Dr. Roselina Arelhi - R.Arelhi@sheffield.ac.uk

#### The University of Liverpool

Graduate Teaching Assistant

- Taught undergraduates in four programmes: mechanical, aerospace, mechatronics and civil engineering.
- Delivered both face-to-face and online teaching sessions.
- Demonstrated practical sessions for engineering modules (nearly 40 laboratory sessions a year).
- Marked students' work using published assessment criteria and provided them with feedback on their progress.

Contact: Dr. Riaz Akhtar - R.Akhtar@liverpool.ac.uk

#### Intel Corp

Static Timing Analyst (Intern)

- Performed full chip timing execution tasks.
- Debugged several issues in the result and flow.
- Developed scripts to automate many of the computationally intensive tasks.

Contact: Mr. Ashish Goel - ashish.kumar.goel@intel.com

## Motorola Solutions Inc & The University of Nottingham

Control Systems Engineer (Trainee)

- Designed and produced a fully functional Anti-lock Braking System (ABS) for automobiles.
- Tested the system in various real driving scenarios.

Contact: Dr. Kevin Lee - In LinkedIn Profile

## **TECHNICAL SKILLS**

ARTIFICIAL INTELLIGENCEData Augmentation | Data Analytics | Natural Language Processing | Deep Learning<br/>C/C++/C# | MATLAB & SIMULINK | Python | TensorFlow & PyTorch | HTML & CSSPROGRAMMINGC/C++/C# | MATLAB & SIMULINK | Python | TensorFlow & PyTorch | HTML & CSSEMBEDDED SYSTEMSWearable Sensors | (Mixed-signal) PCB Design | Sensor Fusion AlgorithmsSOFTWARE DEVELOPMENTUI/UX Design | Sequential/Parallel Processing | Web DevelopmentCOMPUTER SKILLSWindows & Unix OS | 2D/3D CAD | Game Development (3D modelling & animation)Automation & MANUFACTURINGProgrammable Logic Controllers | Subtractive & Additive Manufacturing Processes

## HIGHLIGHTED PROJECTS

## Handmade Smart Socks for Activity Recognition

UNIVERSITY OF LIVERPOOL

- Designed washable pressure-sensitive smart socks purely made of electronically active yarns (e-textile).
- Developed the socks using low-cost processes, such as handmade crochet and knitting.
- Designed and fabricated a small-sized wearable embedded system for sensor data acquisition and transmission.
- Developed an algorithm for step detection and basic activity recognition.

## **Design and Evaluation of Knowledge Exchange in Undergraduate Classrooms** 2020 - 2021 UNIVERSITY OF SHEFFIELD & UNIVERSITY OF LIVERPOOL

- Designed a framework for a group assignment for an engineering module, cultivating knowledge exchange.
- Produced AI-based visualisations of students' knowledge before and after taking the group coursework.
- Recommended evidence-based approaches to foster knowledge exchange in classrooms.

09/2020 - Present | England

06/2017 - 09/2017 | Malaysia

06/2016 - 08/2016 | Malaysia

2022 - 2022

| UNIVERSITY OF LIVERPOOL  |   |   |
|--|---|---|
| <ul> <li>Formulated the clinical proble</li> </ul>   | em in collaboration with an orthopaedic consultant at Aintree U   | Iniversity Hospital.  |
| <ul> <li>Conducted virtual sleep expension</li> </ul>  | riments leveraging on digital 3D animation software.  |   |
| <ul> <li>Proposed novel algorithms for</li> </ul>  | r human body pose tracking during sleep.  |   |
| <ul> <li>Developed custom-made wea</li> </ul>  | arable sensors for in-bed human motion analysis.  |   |
| <ul> <li>Invited human participants to</li> </ul>  | o clinical trials for validating the proposed algorithms.   |   |
| Volitional Control of Upper<br>UNIVERSITY OF NOTTINGHAM  | r Limb Prosthesis for Rehabilitation Services   | 2018 - 20   |
| <ul> <li>Developed a musculoskeletal</li> </ul>  | model of the human upper limb and simulated it under dynam  | nic movements.  |
| <ul> <li>Additively manufactured a co</li> </ul>   | ntrollable biomimetic prosthetic limb.  |   |
| <ul> <li>Applied machine learning for</li> </ul>   | the decoding of non-invasive EMG signals to recognise prosthe   | etic movements.   |
| <ul> <li>Implemented a closed-loop fermion</li> </ul>  | eedback control system to regulate the prosthetic movements.  |   |
| Speaker Recognition Using<br>UNIVERSITY OF NOTTINGHAM  | g Short Incoherent Speech for Health Emergencies  | 2017 - 20   |
| • Proposed a novel short-uttera  | ance speaker identification algorithm using parametric dimensi  | ionality reduction.   |
| • Published two papers as first  | author during the third year of the MEng degree.  |   |
|  |   |   |
| ANGUAGES   | English   | French  |
| Native Proficiency   | Full Working Proficiency  | Basic   |
|  |   |   |
| Guest Lecture: Sensors and   | d Perception in Robotics  | 02/20   |
| <b>Guest Lecture: Sensors and</b><br>University of Sheffield   |   |   |
| Guest Lecture: Sensors and<br>University of Sheffield<br>• Presented the different types   | of robot sensors: proprioceptive, exteroceptive, passive and ac   | ctive sensors.  |
| Guest Lecture: Sensors and<br>University of Sheffield<br>• Presented the different types<br>• Presented common actuator  | of robot sensors: proprioceptive, exteroceptive, passive and ac<br>options in robotics: electrical, pneumatic, hydraulic and soft ac  | ctive sensors.<br>tuators.  |
| Guest Lecture: Sensors and<br>University of Sheffield<br>• Presented the different types<br>• Presented common actuator<br>• Discussed uncertainty of sense  | of robot sensors: proprioceptive, exteroceptive, passive and ac<br>options in robotics: electrical, pneumatic, hydraulic and soft ac<br>sor measurements, sensor fusion techniques, and Bayesian dec  | ctive sensors.<br>tuators.  |
| Guest Lecture: Sensors and<br>University of Sheffield<br>• Presented the different types<br>• Presented common actuator<br>• Discussed uncertainty of sens<br>• Provided students with an over   | of robot sensors: proprioceptive, exteroceptive, passive and ac<br>options in robotics: electrical, pneumatic, hydraulic and soft ac<br>sor measurements, sensor fusion techniques, and Bayesian dec<br>erview of the legal and ethical implications of robotics.   | ctive sensors.<br>tuators.<br>cision making.  |
| Guest Lecture: Sensors and<br>University of Sheffield<br>• Presented the different types<br>• Presented common actuator<br>• Discussed uncertainty of sense<br>• Provided students with an over<br>Guest Speaker: Engineerin   | of robot sensors: proprioceptive, exteroceptive, passive and ac<br>options in robotics: electrical, pneumatic, hydraulic and soft ac<br>sor measurements, sensor fusion techniques, and Bayesian dec<br>erview of the legal and ethical implications of robotics.   | ctive sensors.<br>tuators.<br>cision making.  |
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| Guest Lecture: Sensors and<br>University of Sheffield<br>• Presented the different types<br>• Presented common actuator<br>• Discussed uncertainty of sens<br>• Provided students with an ove<br>Guest Speaker: Engineerin<br>University of Liverpool  | of robot sensors: proprioceptive, exteroceptive, passive and ac<br>options in robotics: electrical, pneumatic, hydraulic and soft ac<br>sor measurements, sensor fusion techniques, and Bayesian dec<br>erview of the legal and ethical implications of robotics.<br><b>Ing Employability Week</b>  | ctive sensors.<br>tuators.<br>cision making.<br>03/20   |
| Guest Lecture: Sensors and<br>University of Sheffield<br>• Presented the different types<br>• Presented common actuator<br>• Discussed uncertainty of sense<br>• Provided students with an ove<br>Guest Speaker: Engineerin<br>University of Liverpool<br>• Shared my experience as a Ph   | of robot sensors: proprioceptive, exteroceptive, passive and ac<br>options in robotics: electrical, pneumatic, hydraulic and soft ac<br>sor measurements, sensor fusion techniques, and Bayesian dec<br>erview of the legal and ethical implications of robotics.<br><b>Ing Employability Week</b>  | ctive sensors.<br>tuators.<br>cision making.<br>03/20   |
| Guest Lecture: Sensors and<br>University of Sheffield<br>• Presented the different types<br>• Presented common actuator<br>• Discussed uncertainty of sens<br>• Provided students with an ove<br>Guest Speaker: Engineerin<br>University of Liverpool<br>• Shared my experience as a Ph<br>Guest Lecture: Stochastic H<br>University of Sheffield  | of robot sensors: proprioceptive, exteroceptive, passive and ac<br>options in robotics: electrical, pneumatic, hydraulic and soft ac<br>sor measurements, sensor fusion techniques, and Bayesian dec<br>erview of the legal and ethical implications of robotics.<br><b>Ing Employability Week</b>  | ctive sensors.<br>tuators.<br>cision making.<br>03/20<br>12/20  |
| Guest Lecture: Sensors and<br>University of Sheffield<br>• Presented the different types<br>• Presented common actuator<br>• Discussed uncertainty of sens<br>• Provided students with an ove<br>Guest Speaker: Engineerin<br>University of Liverpool<br>• Shared my experience as a Ph<br>Guest Lecture: Stochastic H<br>University of Sheffield  | of robot sensors: proprioceptive, exteroceptive, passive and ac<br>options in robotics: electrical, pneumatic, hydraulic and soft ac<br>sor measurements, sensor fusion techniques, and Bayesian dec<br>erview of the legal and ethical implications of robotics.<br><b>Ing Employability Week</b><br>InD student and presented post-PhD career pathways.<br><b>Processes</b><br>graduate students on the probability theory behind stochastic  | ctive sensors.<br>tuators.<br>cision making.<br><i>03/20</i><br>1 <i>2/20</i><br>processes.                   |
| Guest Lecture: Sensors and<br>University of Sheffield<br>• Presented the different types<br>• Presented common actuator<br>• Discussed uncertainty of sense<br>• Provided students with an ove<br>Guest Speaker: Engineerin<br>University of Liverpool<br>• Shared my experience as a Ph<br>Guest Lecture: Stochastic<br>University of Sheffield<br>• Lectured a class of 120 under<br>Guest Speaker: Final Year<br>University of Nottingham   | of robot sensors: proprioceptive, exteroceptive, passive and ac<br>options in robotics: electrical, pneumatic, hydraulic and soft ac<br>sor measurements, sensor fusion techniques, and Bayesian dec<br>erview of the legal and ethical implications of robotics.<br><b>Ing Employability Week</b><br>InD student and presented post-PhD career pathways.<br><b>Processes</b><br>graduate students on the probability theory behind stochastic  | ctive sensors.<br>tuators.<br>cision making.<br>03/20<br>12/20<br>processes.<br>11/20                         |
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• Provided feedback and suggestions for improvement of Elsevier's products & services.

Conducted testing of and assessed Elsevier's newest tools and products against the needs of peer researchers.

## **Academics Across The Globe Initiative** 2020-present UNIVERSITY OF LIVERPOOL & UNIVERSITY OF NOTTINGHAM Founded an online LinkedIn group which brings together academics and early-career researchers. Co-administer the group to assist members in navigating their career pathways, and forming collaborations. **University-wide Green Initiative** 04/2021-10/2021 UNIVERSITY OF LIVERPOOL Designed, built and installed vertical hydroponic systems around the campus to push the sustainability agenda. **Specialised Virtual Engineering Labs** 2020-present UNIVERSITY COLLEGE LONDON, UNIVERSITY OF SHEFFIELD & UNIVERSITY OF LIVERPOOL • Took the initiative to address the lack of well-established digital platforms for engineering practicals. • Formed a team of developers with expertise in immersive digital environments. • Capitalised on game development and gamification to create virtual labs for a better learning experience. • Received positive feedback from academics at The University of Nottingham and The University of Sheffield. Entrepreneurship Course: Build your own business 3 07/2021 - 08/2021 UNIVERSITY COLLEGE LONDON • Won a pitch contest alongside other London students and graduates. • Realised the process of launching a business through interactive workshops and one-to-one mentoring support. • Grasped the different aspects of Intellectual Property, legal matters and startup financing. Entrepreneurship Course: Build your own business 2 05/2021 - 06/2021 UNIVERSITY COLLEGE LONDON • Recognised the tools needed to test the viability of a business idea and develop a business plan. • Learnt the principles of identifying potential markets and target customer segments. Self-learning: System Identification and Parameter Estimation 2018 DELFT UNIVERSITY OF TECHNOLOGY **Self-learning: Bio Mechatronics** 2018 DELFT UNIVERSITY OF TECHNOLOGY Intern Training Course Package 2017 INTEL Privacy Essentials. • Data Leaks Avoidance. • Information Security Awareness. • Export Compliance Written Assurance. edX Course: Introduction to C++ 2016 MICROSOFT CORPORATION **CS4 Qatar for Robotics** 2015 CARNEGIE MELLON UNIVERSITY **First Aid Training** 2015 QATAR CENTRE FOR VOLUNTARY ACTIVITIES **Debate Course** 2014 **GEORGETOWN UNIVERSITY Organising Committee Member for the Following Events:** ROBOTICS SOCIETY, THE UNIVERSITY OF NOTTINGHAM • Arduino workshops for undergraduate students, 2015 THE YOUTH COMPANY, QATAR "Run the World" Festival, 2014 MINISTRY OF CULTURE AND SPORTS, QATAR

• Qatar's Sports Day, 2014

AL-WAKRA INDEPENDENT SECONDARY SCHOOL FOR BOYS, QATAR

- UK Universities Exhibition, 2014
- QATAR CENTRE FOR VOLUNTARY ACTIVITIES
- Volunteer's International Day, 2014

# **Participant in the Following Activities:** INTEL

- Intel Cycling Ride (Silver Medal), 2017
- THE UNIVERSITY OF NOTTINGHAM
- Life Cycle Malaysia 3 (20-Km Charity Ride), 2016
- QATAR FOUNDATION & THE THIMUN FOUNDATION
- Model United Nations (THIMUN), 2015
- AL-WAKRA INDEPENDENT SECONDARY SCHOOL FOR BOYS, QATAR
- School's Scout Team (camping, desert greening, etc.), 2013-2015
- QATAR KARATE FEDERATION
- Qatar's Karate Cup (Silver Medal), 2013

#### **REFERENCES**

## Dr Roselina Arelhi **Director of Learning and Teaching** Department of Automatic Control and Systems Engineering Faculty of Engineering The University of Sheffield Mappin Street Sheffield S1 3JD United Kingdom Telephone: +44 (0) 114 2225136 E-mail: R.Arelhi@sheffield.ac.uk Dr Paolo Paoletti Senior Lecturer Department of Mechanical, Materials and Aerospace Engineering School of Engineering The University of Liverpool **Brownlow Hill** Liverpool L69 3GH United Kingdom Telephone: +44 (0) 151 7945232 E-mail: P.Paoletti@liverpool.ac.uk **Prof Frans Coenen** Professor Department of Computer Science School of Electrical Engineering, Electronics and Computer Science The University of Liverpool Ashton Building, Ashton Street Liverpool L69 3BX United Kingdom Telephone: +44 (0) 151 795 4253 E-mail: Coenen@liverpool.ac.uk